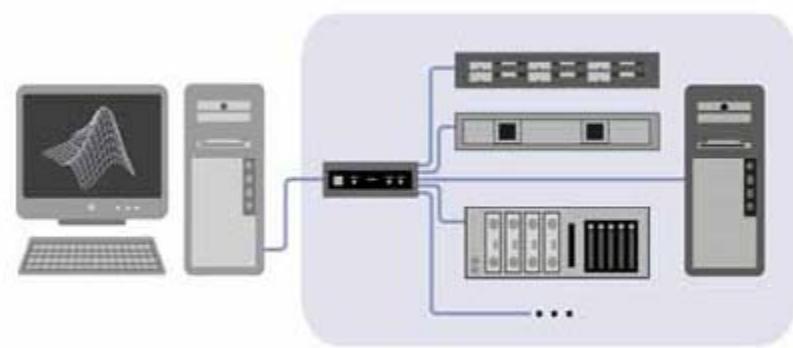


Distributed Computing with MATLAB® and Simulink®

Narfi Stefansson
The MathWorks



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Geospatial Application Accelerated with MATLAB and Distributed Computing

The Challenge

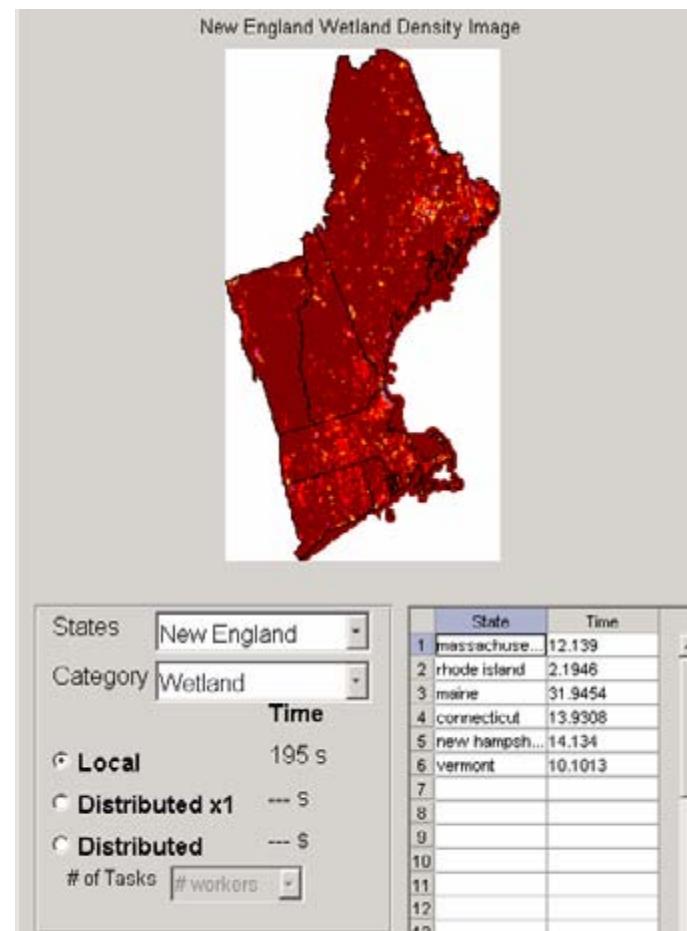
- To compare high-resolution state-by-state land cover maps with lower-resolution U.S. data sets

The Solution

- Use MATLAB®, the Distributed Computing Toolbox, the Image Processing Toolbox, and the Mapping Toolbox to reformulate the original state-by-state land cover data as a single lower resolution U.S. mosaic

The Results

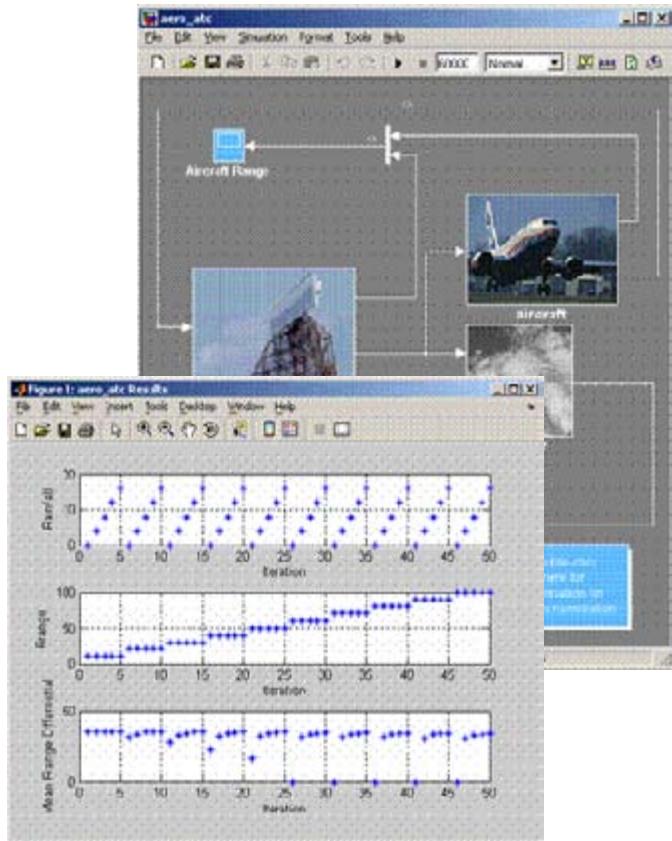
- Computations can run on low-cost computers
- Nearly 4-times speedup on 4 CPUs



http://www.mathworks.com/company/newsletters/news_notes/jan06/distrib.html

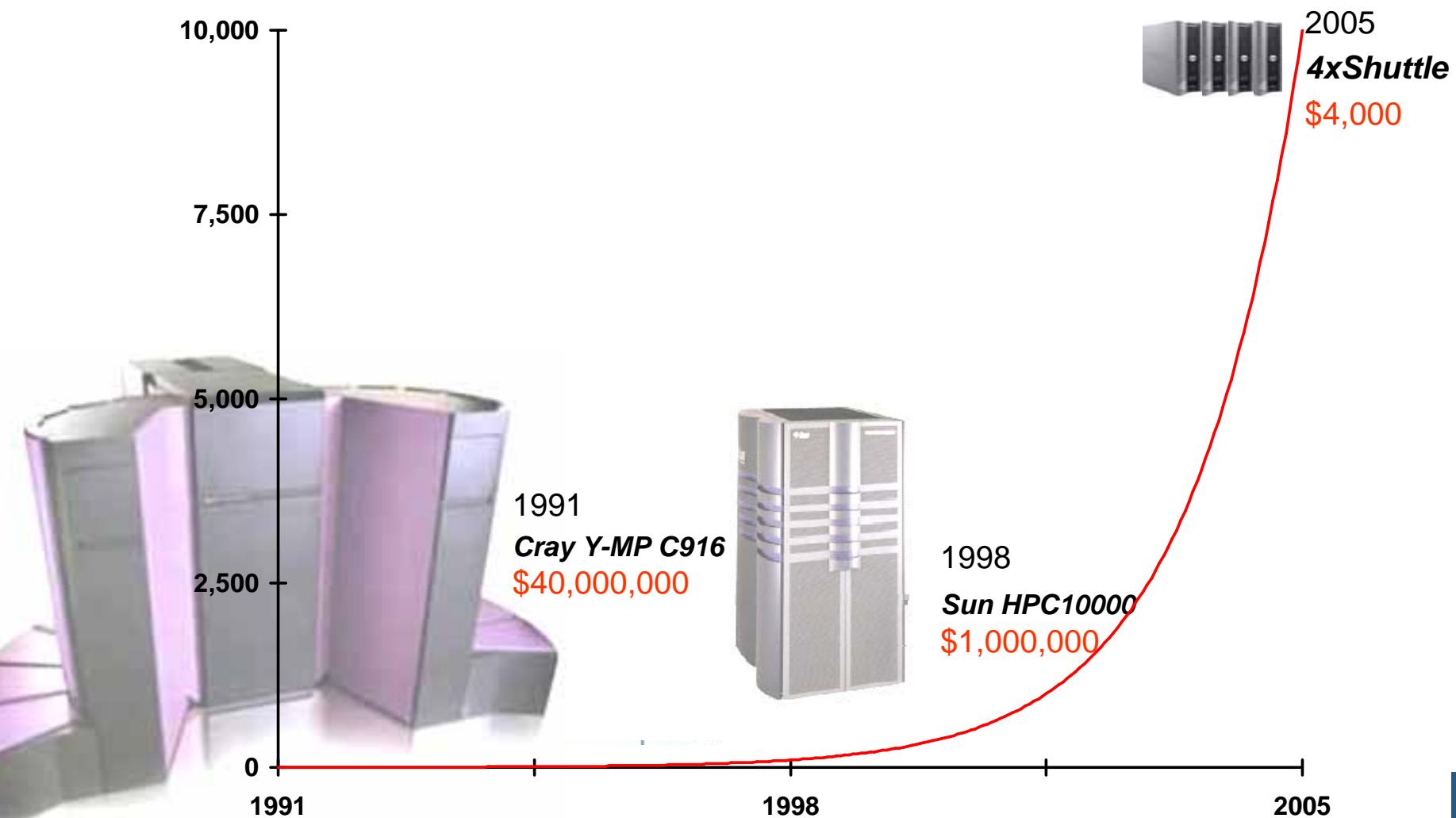
Today's Agenda

- Introduction
- Key features
- Licensing
- Simulink
- Questions and answers

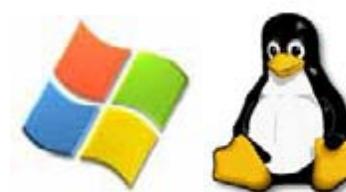
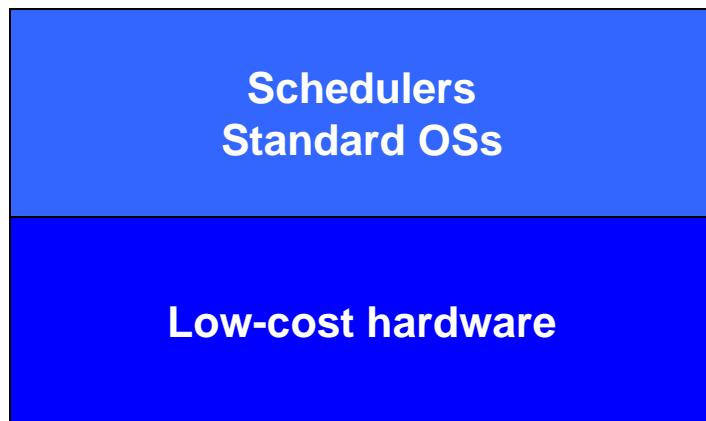


The 10 GFlop Personal Computer

10^4 more power for the money vs. 1991



Standard Operating Systems and Schedulers Now Available



4xShuttle
\$4,000

Standard Engineering Software

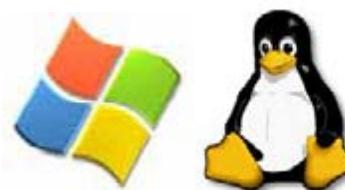
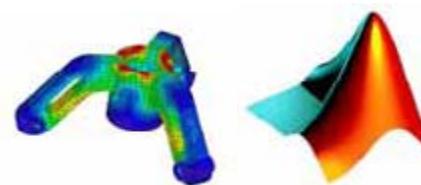
Apply familiar tools to larger tasks

Interactive programming -
re-use of existing applications

Distributed/parallel
engineering software tools

Schedulers
Standard OSs

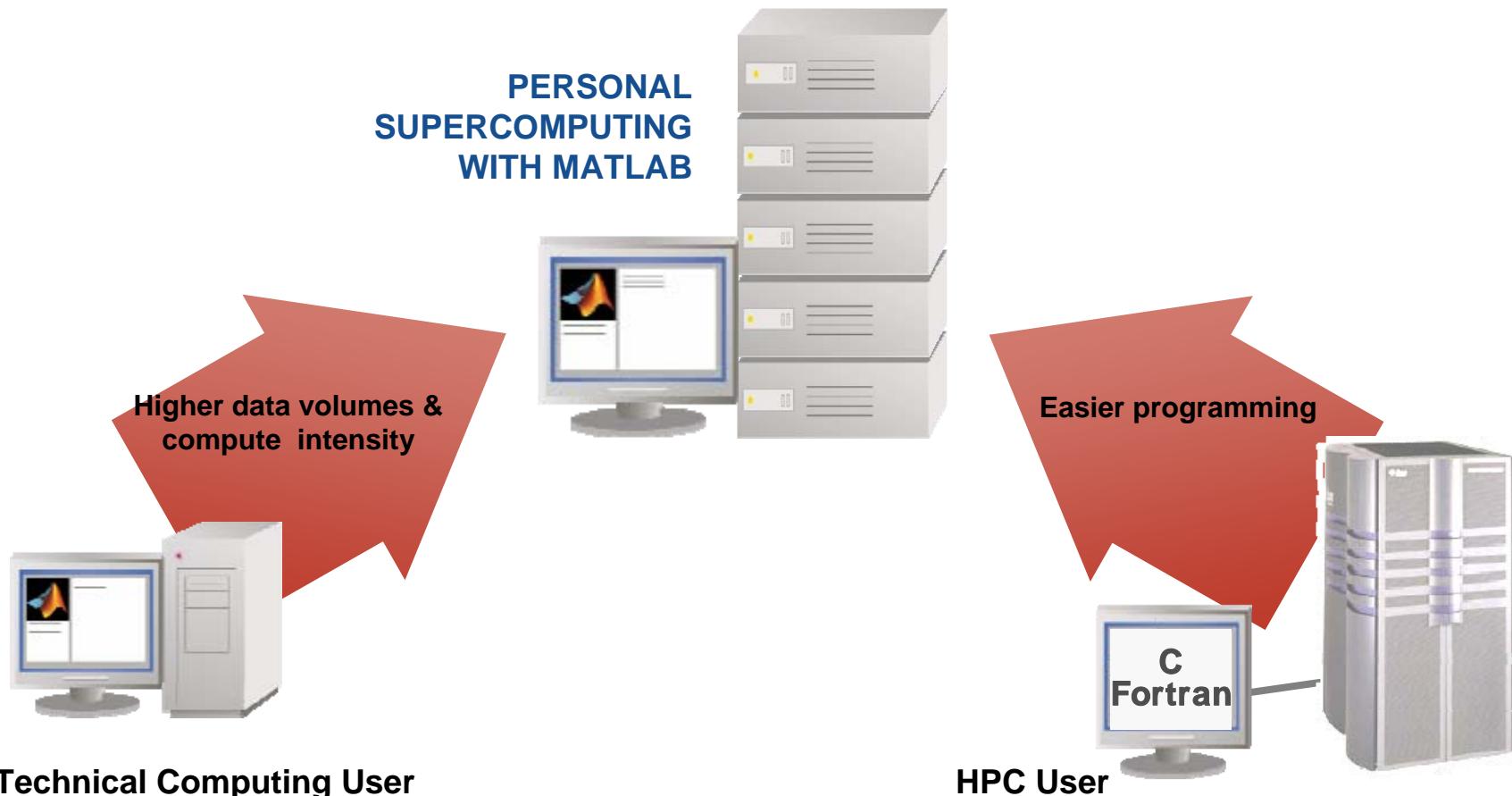
Low-cost hardware



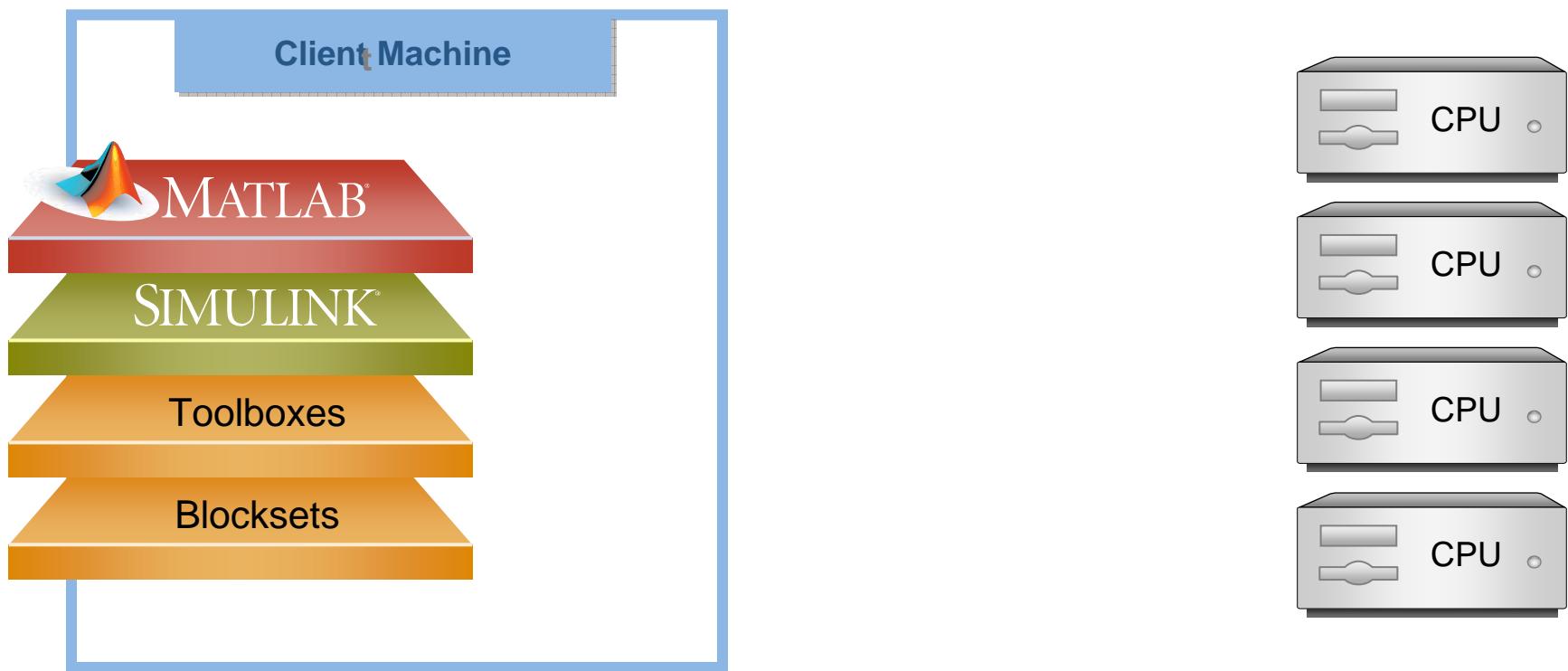
4xShuttle
\$4,000

User Requirements

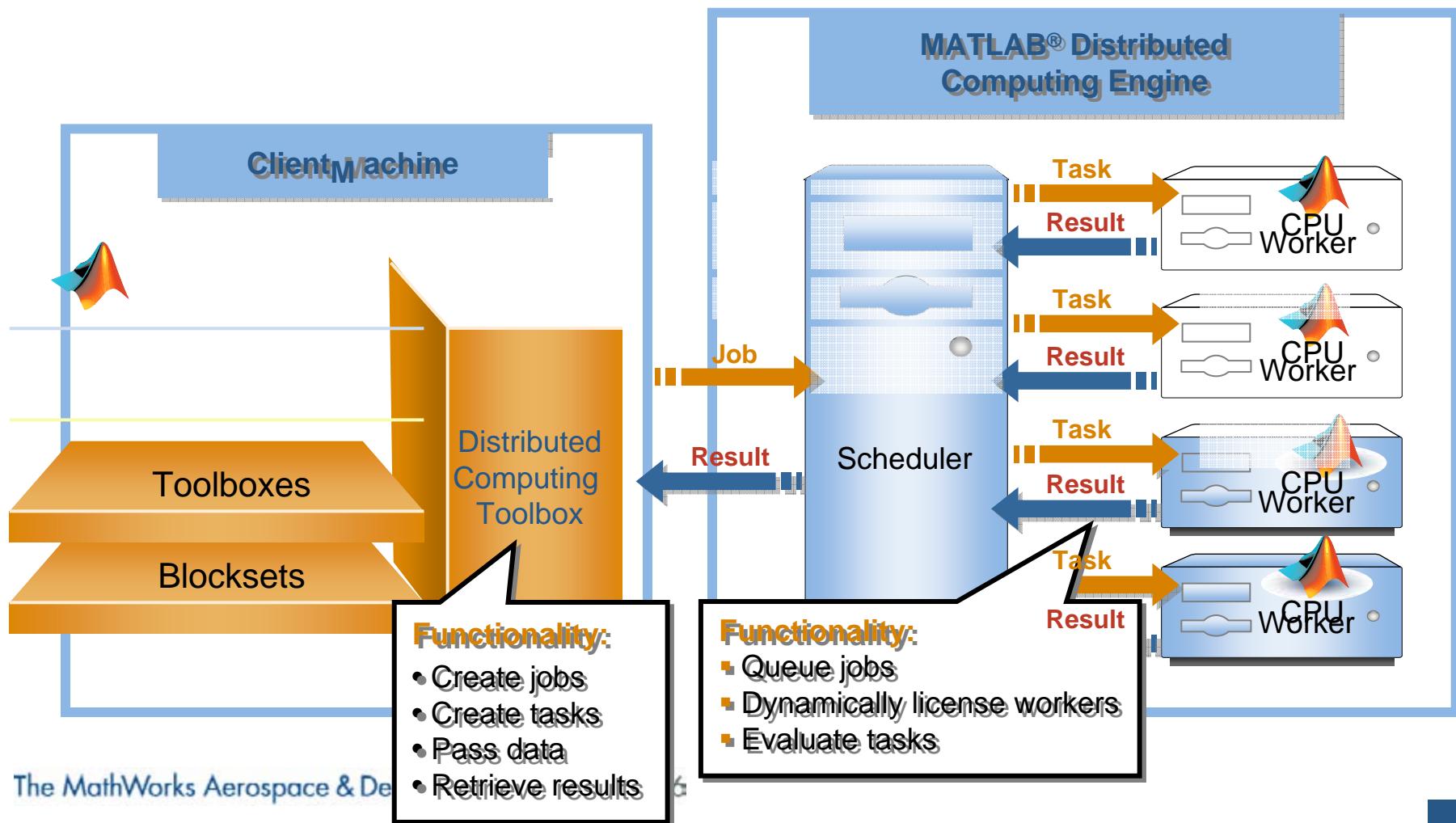
Two user communities



Distributed Computing with MATLAB

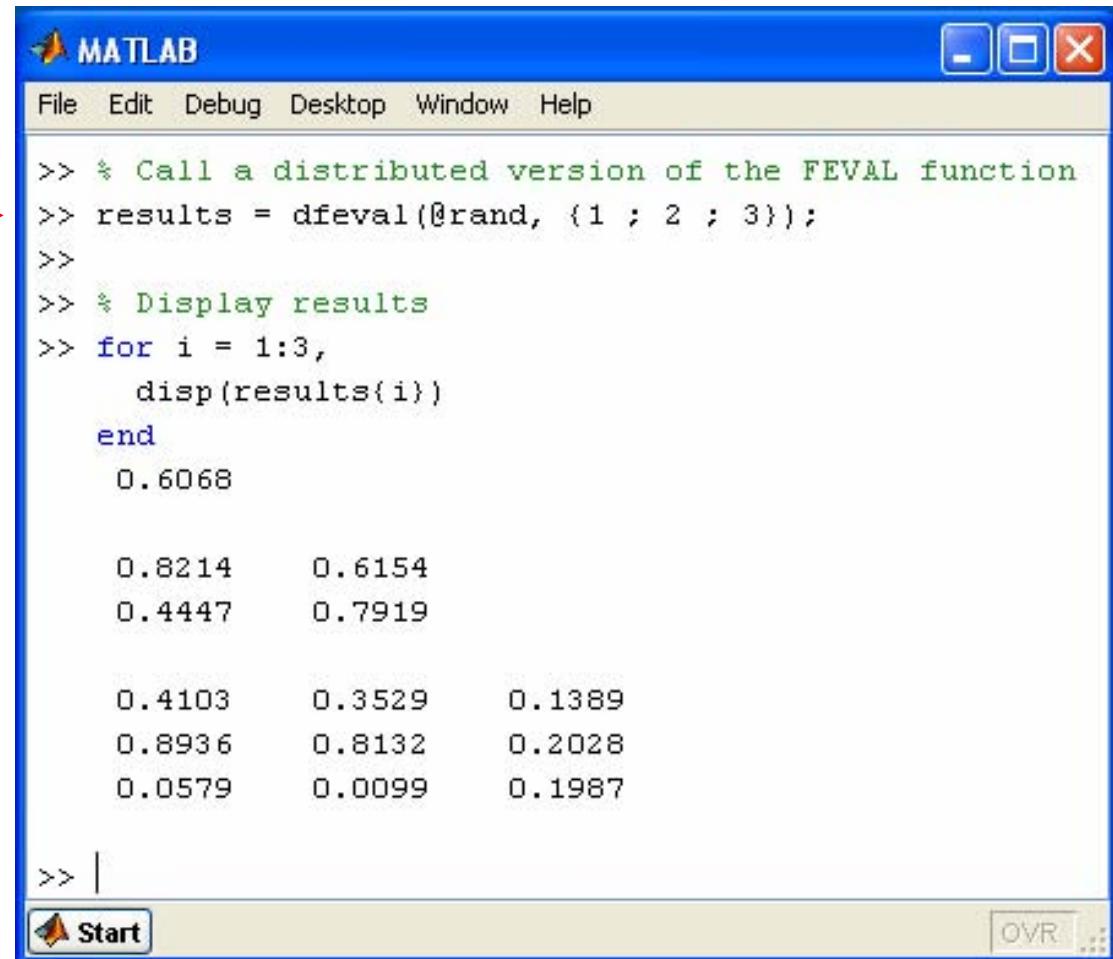


Distributed Computing with MATLAB



Familiar Interface

Function-based
interface



The screenshot shows the MATLAB Command Window with a blue title bar and menu bar. The menu bar includes File, Edit, Debug, Desktop, Window, and Help. The main workspace displays the following MATLAB code and its execution results:

```
>> % Call a distributed version of the FEVAL function
>> results = dfeval(@rand, (1 : 2 : 3));
>>
>> % Display results
>> for i = 1:3,
    disp(results(i))
end
0.6068
0.8214    0.6154
0.4447    0.7919
0.4103    0.3529    0.1389
0.8936    0.8132    0.2028
0.0579    0.0099    0.1987
```

The command prompt at the bottom of the window is >> |.

Full Control Over Job Handling

Object-based interface



```
>> % Find a job manager and create a job
>> jm = findResource('scheduler','type','jobmanager');
>> job = createJob(jm);
>>
>> % Create tasks for the job
>> createTask(job, @rand, 1, {1});
>> createTask(job, @rand, 1, {2});
>> createTask(job, @rand, 1, {3});
>>
>> % Submit the job and wait for it to finish
>> submit(job);
>>waitForState(job, 'finished');
>>
>> % Get results of the job and display them
>> results = getAllOutputArguments(job);
>> for i = 1:3,
    disp(results(i))
end
0.2311

0.0913    0.4565
0.7621    0.0185

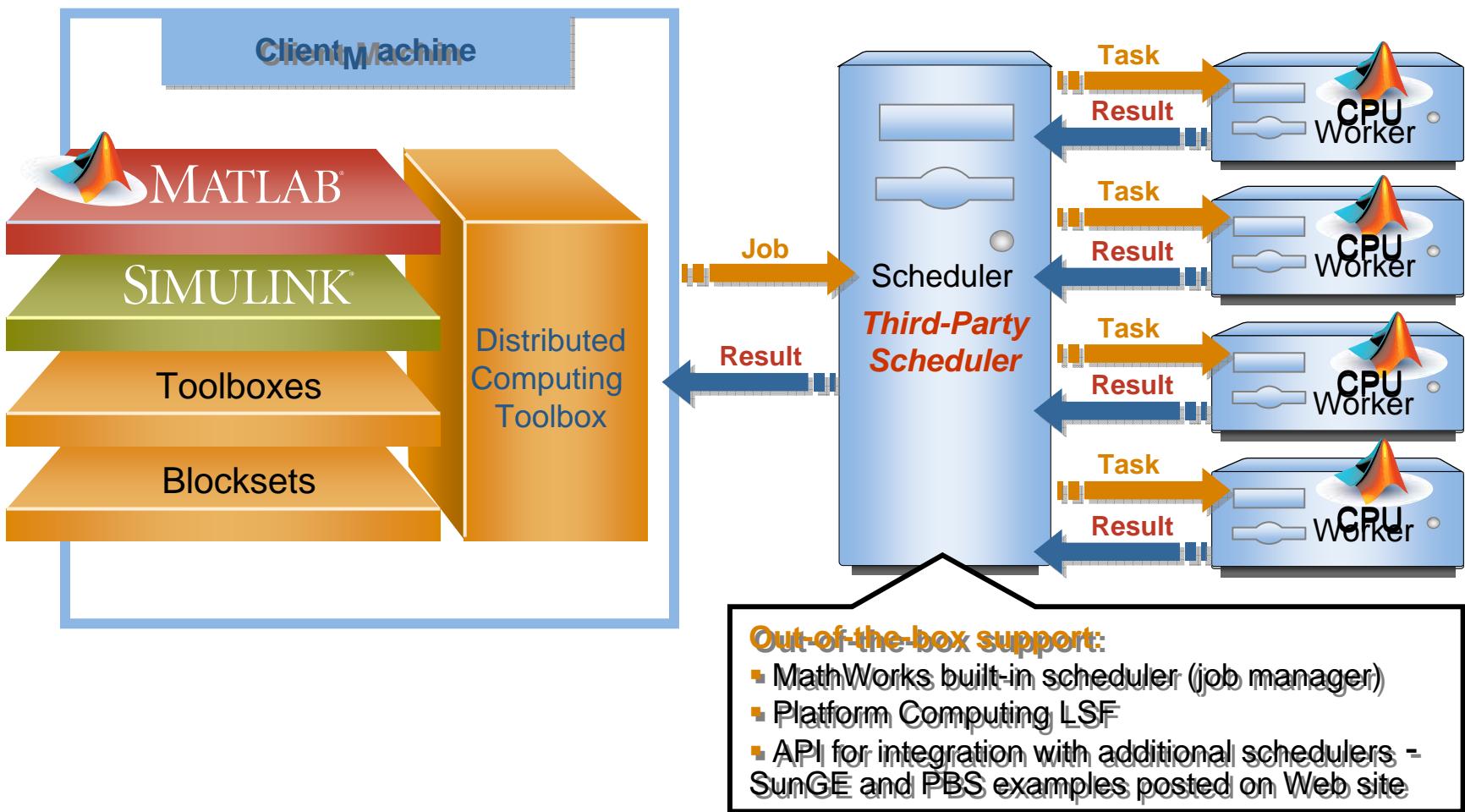
0.4447    0.9218    0.4057
0.6154    0.7382    0.9355
0.7919    0.1763    0.9169

>>
```

Other Key Features

- Schedulers
- Parallel applications
- Varied modes of interaction
- Hardware

Support for Third-Party Schedulers



Benefits of Scheduler Integration

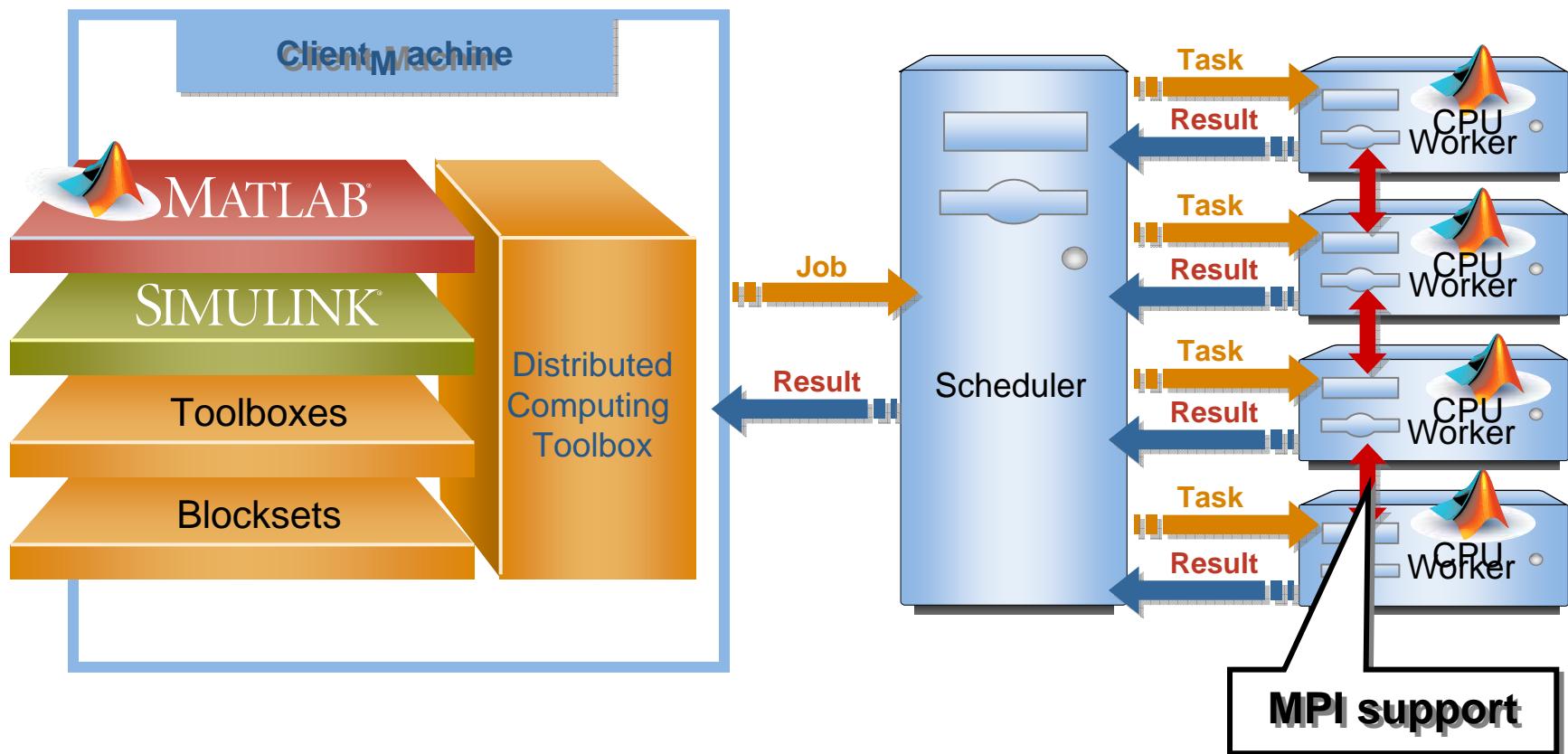
- Take advantage of the scheduler unique capabilities
 - Advanced scheduling
 - Batch workflow support
 - Utilization and performance increase
 - Scalability, reliability, and security
- Run MATLAB and other applications on same cluster
 - Increased throughput
 - Reduced costs of ownership

Simple to Customize for Third-Party Schedulers

Command Window

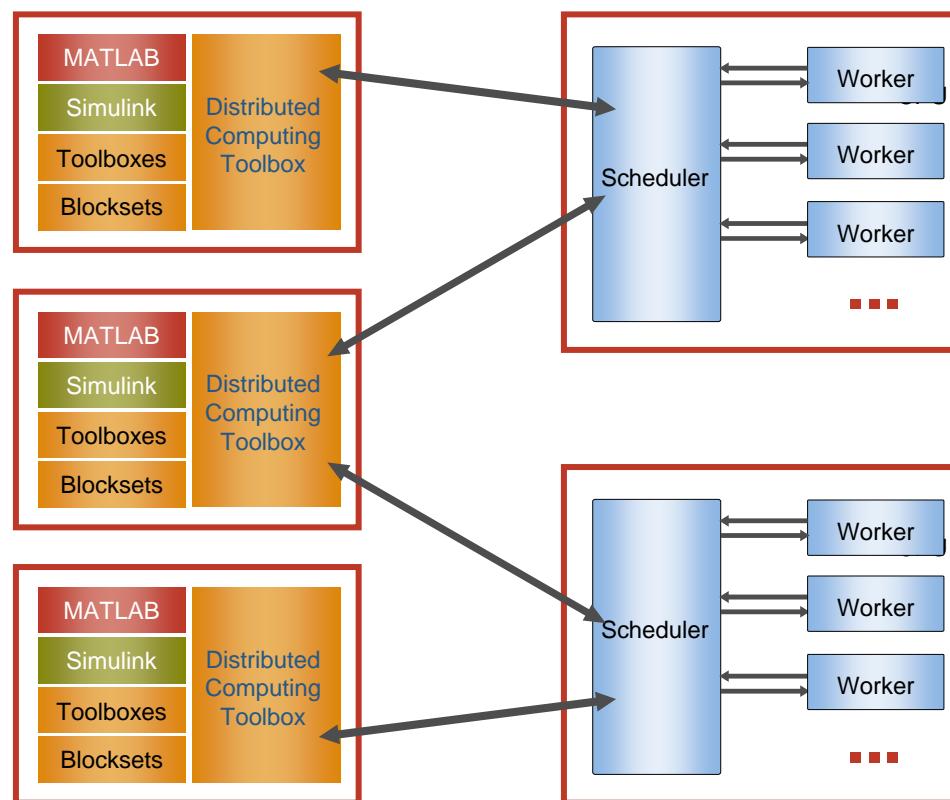
```
>> sched = findResource('scheduler', 'type', 'lslf');
>> set(sched, 'DataLocation', '/scratch/lslf_jobs');
>> job = createJob(sched);
>> createTask(job, @sum, 1, {1:10});
>> submit(job);
>> get(sched)
    Type: 'lslf'
    DataLocation: '/scratch/lslf_jobs'
```

Support for Parallel Applications



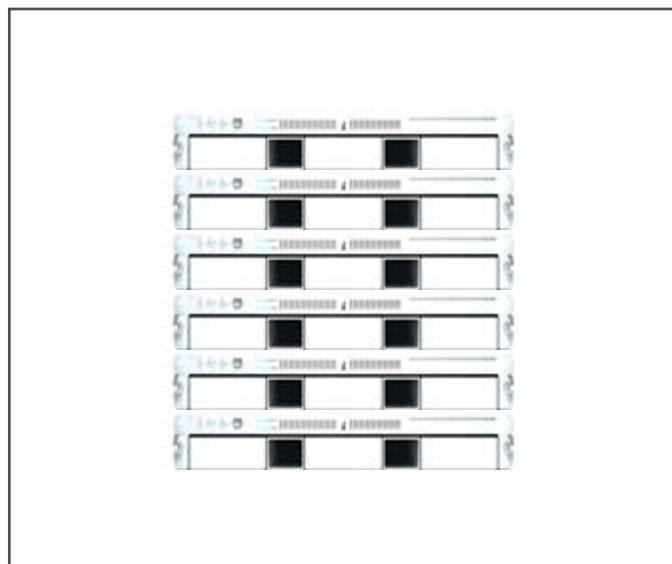
Versatile Modes of Access

Access to single or multiple clusters by single or multiple users
(one to many, many to one)

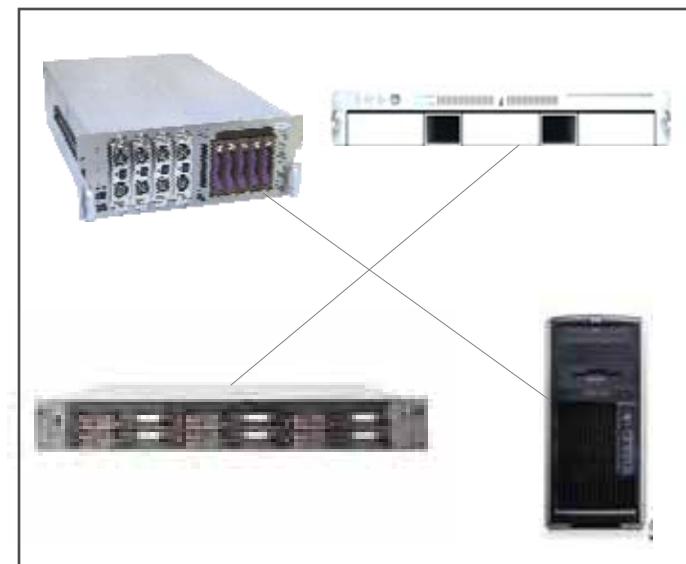


Heterogeneous Platform Support

Support for all platforms that MATLAB supports



Homogeneous cluster

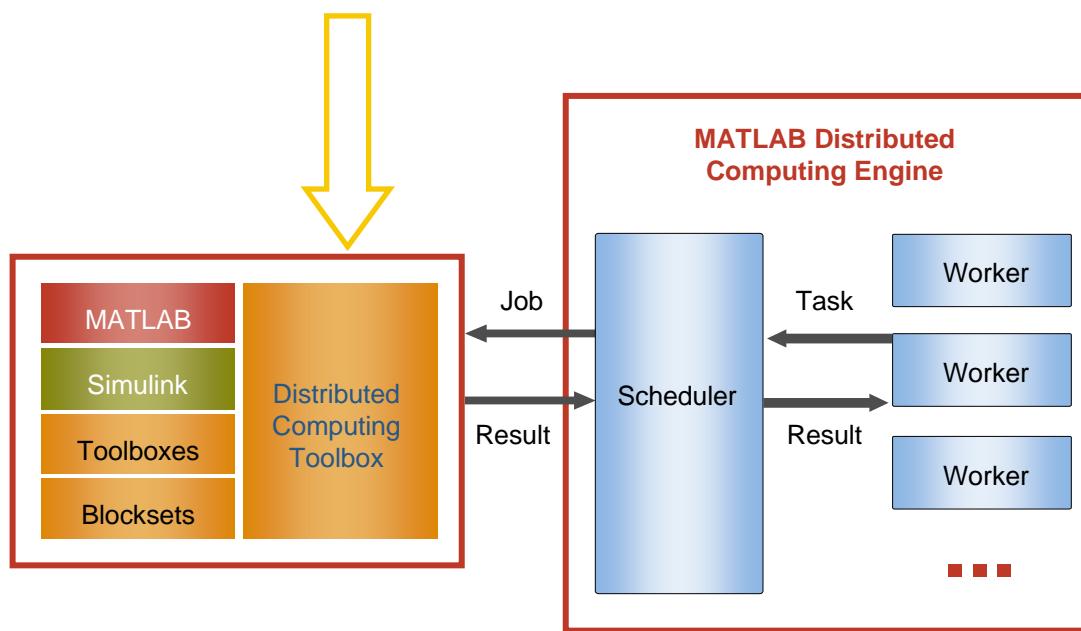


Heterogeneous cluster

Distributed Computing Toolbox

Licensed like any other toolbox

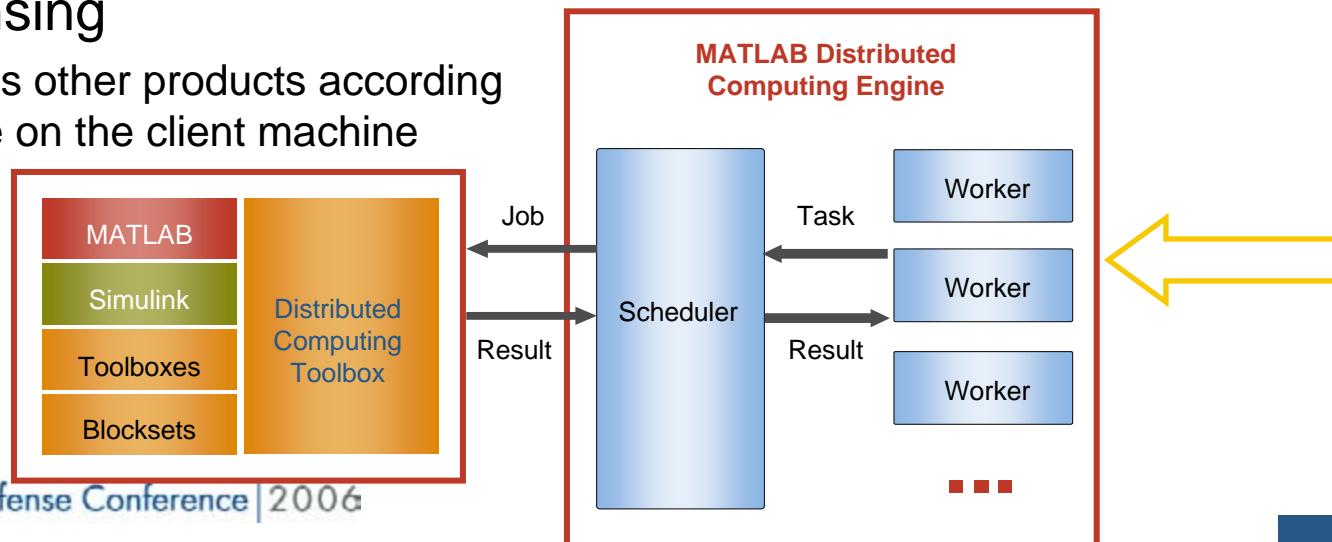
- Individual, concurrent, group
- Requires MATLAB



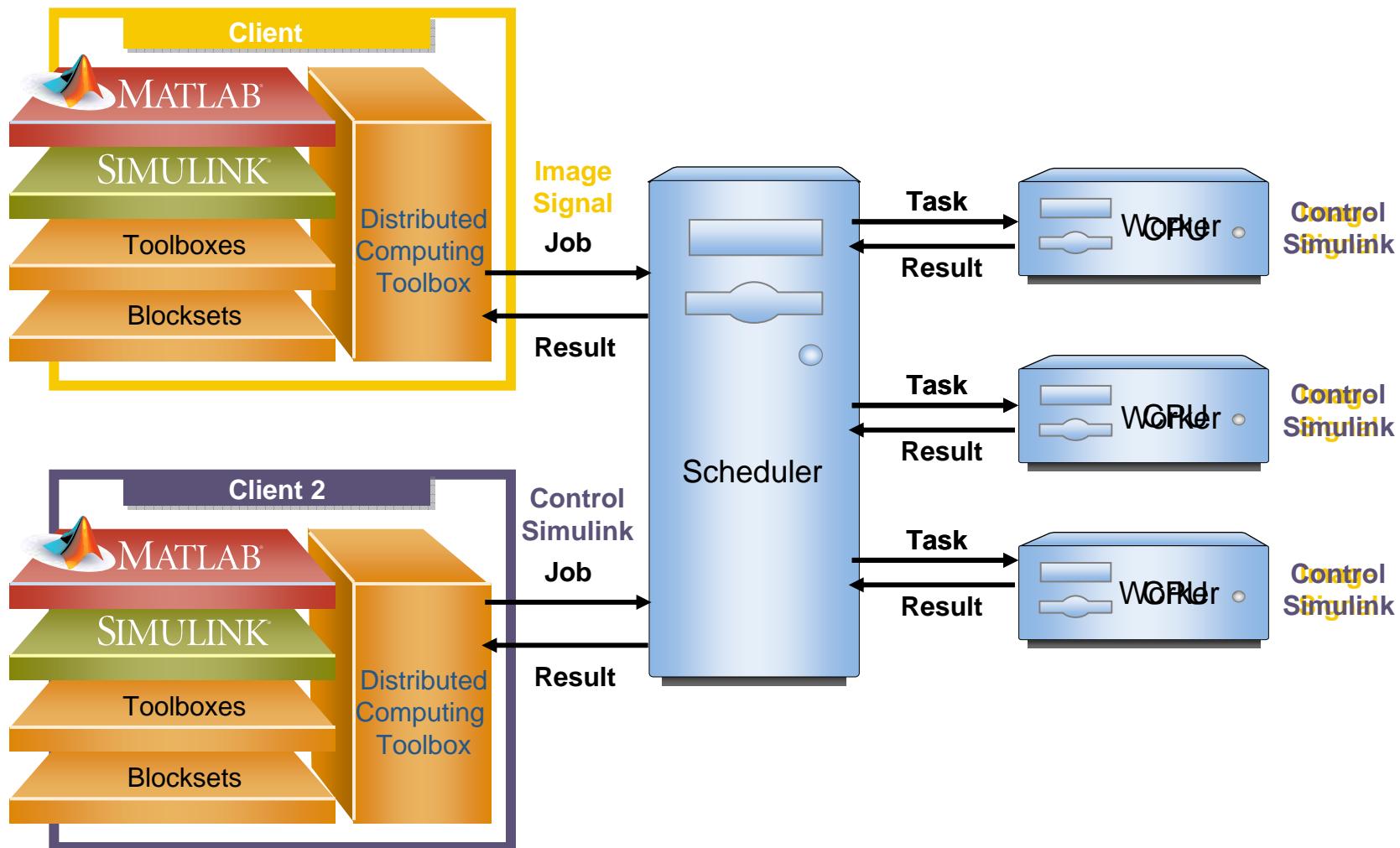
MATLAB Distributed Computing Engine

Cost-efficient licensing

- One key required per worker (to MATLAB session, not a processor)
 - Sold in packs of 8, 16, 32, 64, 96, 128, etc.
 - Scheduler not license managed
- All-product install
 - Code generation and deployment products excluded
 - Simulink and related products do not work with MPI
- Dynamic licensing
 - Engine enables other products according to user license on the client machine



Dynamic Licensing



Research Engineers Advance Design of the International Linear Collider with MathWorks Tools

The Challenge

To design a control system for ensuring the precise alignment of particle beams in the International Linear Collider

The Solution

Use MATLAB, Simulink, the Distributed Computing Toolbox, and the Instrument Control Toolbox to design, model, and simulate the accelerator and alignment control system

The Results

- Simulation time reduced by an order of magnitude
- Development integrated
- Existing work leveraged



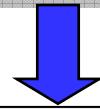
Queen Mary high-throughput cluster.

“Using the Distributed Computing Toolbox, we simply deployed our simulation on a large group cluster. We saw a linear improvement in speed, and we could run 100 simulations at once. MathWorks tools have enabled us to accomplish work that was once impossible.”

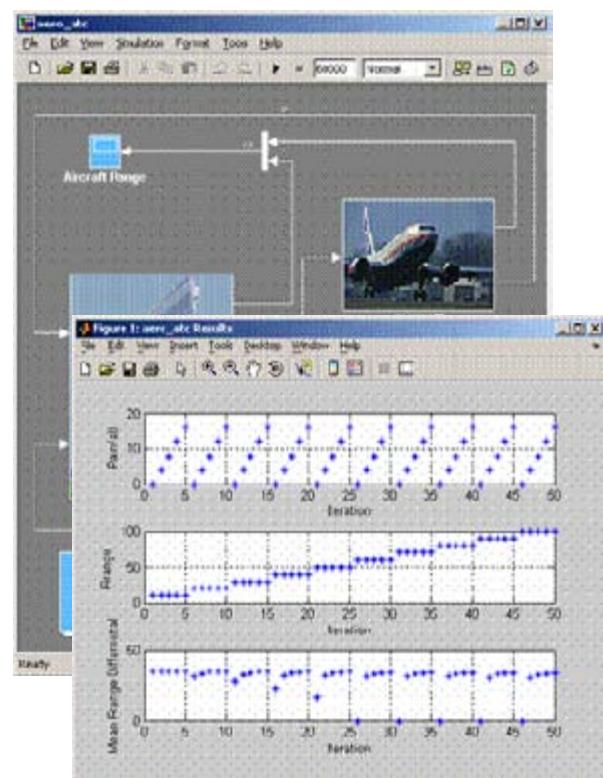
Dr. Glen White,
Queen Mary, University of London

Applying Distributed Computing to Simulink

```
for lp = 1:nSims,  
    results{lp}=sim('model', ...)  
end  
end
```



```
results = dfeval(@simunit,{nSims});  
  
function results=simUnit  
results=sim('model', ...)
```

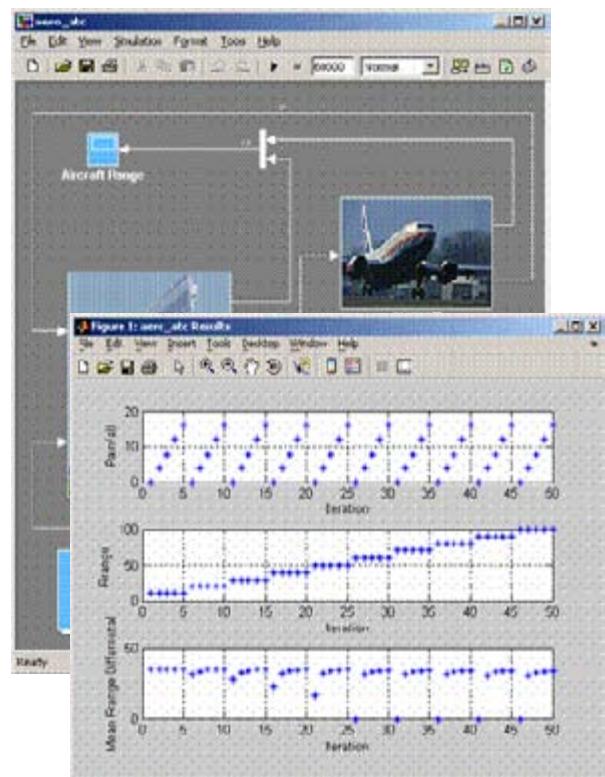


Applying distributed computing to Simulink

```
for lp = 1:nSims,  
    results{lp}=sim('model', ...)  
end  
end
```



```
sched = findResource(...);  
job=createJob(sched);  
for lp = 1:nSims,  
    createTask(job,@simUnit, ...)  
end  
submit(job)  
waitForState(job,'finished');  
results = getAllOutputArguments(job);  
  
function results=simUnit  
results=sim('model', ...)
```



Distributed Computing Tools Summary

- Increase productivity by reducing the development time of distributed applications
- Improve performance
 - Easy to develop distributed MATLAB applications
 - Third-party scheduler support
 - Distributed and parallel execution
 - Dynamic licensing
- Preview an upcoming release in exhibit hall

Questions?

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Aerospace & Defense Conference | 2006