Large Model Simulation in Simulink® Models Using Legacy Code Tool

>Aircraft engine generic simulation example
>Pros, cons, and issues

Dave Gutz, Principal Engineer GE Aviation, Lynn, Mass

magination at work



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Requirements Summary

- 1. Automatically create a Simulink block representing legacy code
- 2. Inputs of the block consist of
 - ID flag
 - Inputs including data bus
 - Dynamic adjustments to internal code
 - Outputs of the block consist of all parameters in one bus to be used for debugging scopes as well as real interfaces
- 2. Automatically create a separate Simulink block representing block adjustments.
- 3. Automatically create a separate Matlab bus definition file defining
 - global common structure
 - adjustment structure
 - Inputs structure
- 4. Provide for incremental compilation.
- 5. Provide for block adjustment changes in a separate user-edited file. Initially for any given build, this file is blank and default values are used automatically and built-in to the block code.
- 6. Work with standard installation of Microsoft Visual C++ compiler (.NET)



Model In Use in Simulation





Input Interface



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Incremental Compilation Features

- •Minimize design cycle time (logic drawing \rightarrow simulation)
- •Use file time-stamps
- •Save build history in .mat files.
- •Saves parameter definitions in .mat files to detect additions
- •CVS configuration management preserves time-stamps
- •Writes and manages Bus Objects file
- •Writes and manages the automatically generated interface files



Pitfalls

•IPC synchronization between DOS processes and Matlab simulations can result in commons mismatch and SEG faults, or worse, bad results without compiler warnings.

- •Barebones legacy code tool does not manage states – use trimmers to initialize
- Incomplete data type support
- •Debug compilation will not produce symbolic info
- •RT block interactions with bus not understood (solve with update specifications to legacy tool)

